

# **OPC 10000-10**

# **OPC Unified Architecture**

# Part 10: Programs

Release 1.04

2017-11-01

Specification Type:	Industry Standard Specification	Comments:	Report or view errata: http://www.opcfoundation.org/errata
Document Number	OPC 10000-10		
Title:	OPC Unified Architecture	Date:	2017-11-01
	Part 10 :Programs		
Version:	Release 1.04	Software: Source:	MS-Word OPC 10000-10 - UA Specification
			Part 10 - Programs 1.04.docx
Author:		Status:	Release

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# UNIFIED ARCHITECTURE –

#### FOREWORD

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# **Revision 1.4 Highlights**

The following table includes the Mantis issues resolved with this revision.

Mantis ID	Summary	Resolution	
<u>3165</u>	Wrong variable data types in Program example.	Fixed datatypes and replaced Table A.14 by description of the variables.	
<u>3521</u>	Modelling rules for states and transitions.	Removed the modelling rules from state and transition objects as they are never created (multiple tables).	
<u>3522</u>	Wrong BrowseNames	In figure 6, changed from StartInputArguments and StartOutputArguments to just InputArguments and OutputArguments.	
<u>3520</u>	Naming of ProgramType	Changed ProgramType to ProgramStateMachineType as suggested. This is also in line with the NodeSet.	
<u>3576</u>	Invalid data type for argument value	In ProgramDiagnosticDataType - changed the definition of lastInputArguments and lastOutputArguments and added two additional fields for the argument values. Also changed StatusResult into StatusCode. Created new version of the type to	
		ProgramDiagnostic2DataType.	
<u>3577</u>	The standard methods have no arguments but sub-types might.	Added OptionalPlaceHolder as Reference for these Methods. Following the clarification in Part 3 this now allows subtypes (or instances) to add arguments	
<u>3927</u>	Make statenumbers in ProgramStatemachineType consistent between spec and NodeSet	To avoid erroneous interpretation, the state numbers are changed from 1, 2, 3, 4 into 11, 12, 13, 14 in spec and NodeSet.	

# **OPC Unified Architecture Specification**

# Part 10: Programs

#### 1 Scope

This specification is part of the overall OPC Unified Architecture (OPC UA) standard series and defines the *information model* associated with *Programs*. This includes the description of the *NodeClasses*, standard *Properties*, *Methods* and *Events* and associated behaviour and information for *Programs*.

The complete address space model including all *NodeClasses* and *Attributes* is specified in OPC 10000-3. The *Services* such as those used to invoke the *Methods* used to manage *Programs* are specified in OPC 10000-4.

#### 2 Normative references

The following documents, in whole or in part, are normatively referenced in this document and are indispensable for its application. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments and errata) applies.

- OPC 10000-1, OPC Unified Architecture Part 1: Overview and Concepts http://www.opcfoundation.org/UA/Part1/
- OPC 10000-3, OPC Unified Architecture Part 3: Address Space Model http://www.opcfoundation.org/UA/Part3/
- OPC 10000-4, OPC Unified Architecture Part 4: Services http://www.opcfoundation.org/UA/Part4/
- OPC 10000-5, OPC Unified Architecture Part 5: Information Model http://www.opcfoundation.org/UA/Part5/
- OPC 10000-7, OPC Unified Architecture Part 7: Profiles http://www.opcfoundation.org/UA/Part7/

#### 3 Terms, definitions and conventions

#### 3.1 Terms and definitions

For the purposes of this document, the terms and definitions given in The following documents, in whole or in part, are normatively referenced in this document and are indispensable for its application. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments and errata) applies.

OPC 10000-1, OPC 10000-3, as well as the following apply.

#### 3.1.1

#### Function

programmatic task performed by a *Server* or device, usually accomplished by computer code execution

#### 3.1.2

#### Finite State Machine

sequence of states and valid state transitions along with the causes and effects of those state transitions that define the actions of a *Program* in terms of discrete stages

## 3.1.3

#### ProgramStateMachineType

type definition of a *Program* and is a subtype of the *FiniteStateMachineType* 

#### 3.1.4

#### Program Control Method

*Method* having specific semantics designed for the control of a *Program* by causing a state transition

#### 3.1.5

#### **Program Invocation**

unique Object instance of a Program existing on a Server

Note 1 to entry: A *Program Invocation* is distinguished from other *Object* instances of the same *ProgramStateMachineType* by the object node's unique browse path.

#### 3.2 Abbreviations

- DA Data Access
- FSM Finite State Machine
- HMI Human Machine Interfaces
- UA Unified Architecture

#### 4 Concepts

#### 4.1 General

Integrated automation facilities manage their operations through the exchange of data and the coordinated invocation of system *Functions* as illustrated in Figure 1. *Services* are required to perform the data exchanges and to invoke the *Functions* that constitute system operation. These *Functions* may be invoked through Human Machine Interfaces, cell controllers, or other supervisory control and data acquisition type systems. OPC UA defines *Methods* and *Programs* as an interoperable way to advertise, discover, and request these *Functions*. They provide a normalizing mechanism for the semantic description, invocation, and result reporting of these *Functions*. Together *Methods* and *Programs* complement the other OPC UA *Services* and *ObjectTypes* to facilitate the operation of an automation environment using a client-server hierarchy.

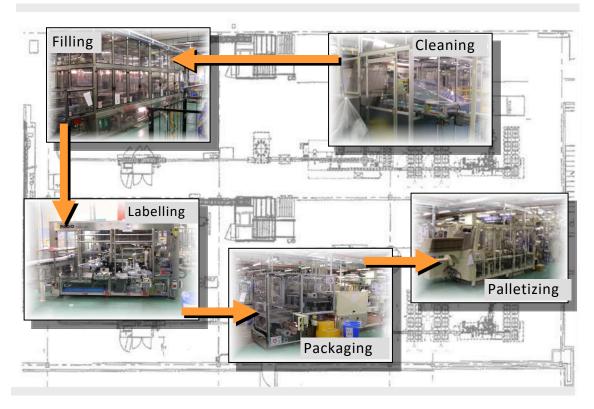


Figure 1 – Automation facility control

*Methods* and *Programs* model *Functions* typically have different scopes, behaviours, lifetimes, and complexities in *OPC Servers* and the underlying systems. These *Functions* are not normally characterized by the reading or writing of data which is accomplished with the OPC UA A *ttribute* service set.

*Methods* represent basic *Functions* in the *Server* that can be invoked by a *Client. Programs*, by contrast, model more complex and stateful functionality in the system. For example, a method call may be used to perform a calculation or reset a counter. A *Program* is used to run and control a batch process, execute a machine tool part program, or manage a domain download. *Methods* and their invocation mechanism are described in OPC 10000-3 and OPC 10000-4.

This standard describes the extensions to, or specific use of, the core capabilities defined in OPC 10000-5 as required for *Programs*.

#### 4.2 Programs

#### 4.2.1 Overview

*Programs* are complex *Functions* in a *Server* or underlying system that can be invoked and managed by a *Client*. *Programs* can represent any level of functionality within a system or process in which *Client* control or intervention is required and progress monitoring is desired. Figure 2 illustrates the model.

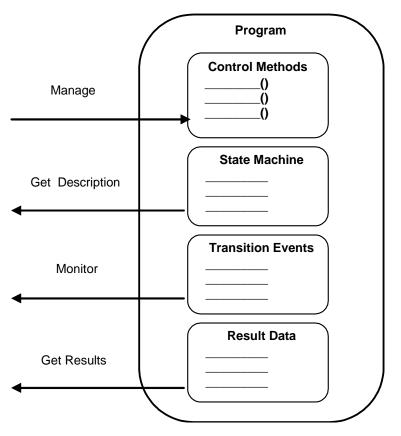


Figure 2 – Program illustration

*Programs* are stateful and transition through a prescribed sequence of states as they execute. Their behaviour is defined by a *Program Finite State Machine (PFSM)*. The elements of the PFSM describe the phases of a *Program's* execution in terms of valid transitions between a set of states, the stimuli or causes of those transitions, and the resultant effects of the transitions.

#### 4.2.2 Security considerations

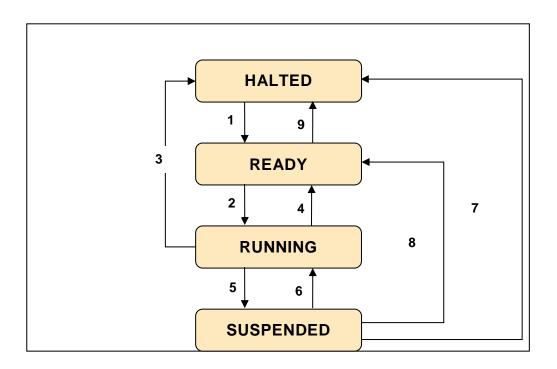
Since *Programs* can be used to perform advanced control algorithms or other actions, their use should be restricted to personnel with appropriate access rights. It is recommended that *AuditUpdateMethodEvents* are generated to allow monitoring the number of running *Programs* in addition to their execution frequency.

#### 4.2.3 Program Finite State Machine

The states, transitions, causes and effects that compose the *Program Finite State Machine* are listed in Table 1 and illustrated in Figure 3.

No.	Transition name	Cause	From state	To state	Effect
1	HaltedToReady	Reset Method	Halted	Ready	Report Transition 1 Event/Result
2	ReadyToRunning	Start Method	Ready	Running	Report Transition 2 Event/Result
3	RunningToHalted	Halt Method or Internal (Error)	Running	Halted	Report Transition 3 Event/Result
4	RunningToReady	Internal	Running	Ready	Report Transition 4 Event/Result
5	RunningToSuspended	Suspend Method	Running	Suspended	Report Transition 5 Event/Result
6	SuspendedToRunning	Resume Method	Suspended	Running	Report Transition 6 Event/Result
7	SuspendedToHalted	Halt Method	Suspended	Halted	Report Transition 7 Event/Result

No.	Transition name	Cause	From state	To state	Effect
8	SuspendedToReady	Internal	Suspended	Ready	Report Transition 8 Event/Result
9	ReadyToHalted	Halt Method	Ready	Halted	Report Transition 9 Event/Result



#### Figure 3 – Program states and transitions

# 4.2.4 Program states

A standard set of base states is defined for *Programs* as part of the *Program Finite State Machine.* These states represent the stages in which a *Program* can exist at an instance in time as viewed by a *Client*. This state is the *Program's* current state. All *Programs* shall support this base set. A *Program* may or may not require a *Client* action to cause the state to change. The states are formally defined in Table 2.

State	Description
ReadyThe Program is properly initialized and may be started.	
Running         The Program is executing making progress towards completion.	
Suspended	The <i>Program</i> has been stopped prior to reaching a terminal state but may be resumed.
Halted	The <i>Program</i> is in a terminal or failed state, and it cannot be started or resumed without being reset.

#### Table 2 – Program states

The set of states defined to describe a *Program* can be expanded. *Program* sub states can be defined for the base states to provide more resolution of a process and to describe the cause and effect(s) of additional stimuli and transitions. Standards bodies and industry groups may extend the base *Program Finite State Model* to conform to various industry models. For example, the Halted state can include the sub states "Aborted" and "Completed" to indicate if the *Function* achieved a successful conclusion prior to the transition to Halted. Transitional states such as "Starting" or "Suspending" might also be extensions of the Running state, for example.

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#### 4.2.5 State transitions

A standard set of state transitions is defined for the *Program Finite State Machine*. These transitions define the valid changes to the *Program's* current state in terms of an initial state and a resultant state. The transitions are formally defined in Table 3.

Transition no.	Transition name	Initial state	Resultant state
1	HaltedToReady	Halted	Ready
2	ReadyToRunning	Ready	Running
3	RunningToHalted	Running	Halted
4	RunningToReady	Running	Ready
5	RunningToSuspended	Running	Suspended
6	SuspendedToRunning	Suspended	Running
7	SuspendedToHalted	Suspended	Halted
8	SuspendedToReady	Suspended	Ready
9	ReadyToHalted	Ready	Halted

Table 3 – Program	state transitions
-------------------	-------------------

#### 4.2.6 Program state transition stimuli

The stimuli or causes for a *Program's* state transitions can be internal to the *Server* or external. The completion of machining steps, the detection of an alarm condition, or the transmission of a data packet are examples of internal stimuli. *Methods* are an example of external stimuli. Standard *Methods* are defined which act as stimuli for the control of a *Program*.

#### 4.2.7 Program Control Methods

*Clients* manage a *Program* by calling *Methods*. The *Methods* impact a *Program's* behaviour by causing specified state transitions. The state transitions dictate the actions performed by the *Program*. This standard defines a set of standard *Program Control Methods*. These *Methods* provide sufficient means for a *Client* to run a *Program*.

Table 4 lists the set of defined *Program Control Methods*. Each *Method* causes transitions from specified states and shall be called when the *Program* is in one of those states.

Individual *Programs* can optionally support any subset of the *Program Control Methods*. For example, some *Programs* may not be permitted to suspend and so would not provide the *Suspend* and *Resume Methods*.

*Programs* can support additional user defined *Methods*. User defined *Methods* shall not change the behaviour of the base *Program Finite State Machine*.

Method Name	ame Description					
Start	Causes the Program to transition from the Ready state to the Running state.					
Suspend	Causes the <i>Program</i> to transition from the Running state to the Suspended state.					
Resume	Causes the Program to transition from the Suspended state to the Running state.					
Halt	Causes the <i>Program</i> to transition from the Ready, Running or Suspended state to the Halted state.					
Reset	Causes the Program to transition from the Halted state to the Ready state.					

#### Table 4 – Program Control Methods

Program Control Methods are defined with their BrowseName All on the ProgramStateMachineType with the OptionalPlaceholder ModellingRule. As defined in OPC 10000-3, this rule allows the inclusion of Arguments to these Methods on sub-types or on instances. For example, a Start Method may include an options argument that specifies dynamic options used to determine some program behaviour. The Method Call service specified in OPC 10000-4 defines a return status. This return status indicates the success of the Program Control Method or a reason for its failure.

#### 4.2.8 **Program state transition effects**

A *Program's* state transition generally has a cause and also yields an effect. The effect is a by product of a *Program* state transition that can be used by a *Client* to monitor the progress of the *Program*. Effects can be internal or external. An external effect of a state transition is the generation of an *Event* notification. Each *Program* state transition is associated with a unique *Event*. These *Events* reflect the progression and trajectory of the *Program* through its set of defined states. The internal effects of a state transition can be the performance of some programmatic action such as the generation of data.

#### 4.2.9 Program result data

#### 4.2.9.1 Overview

Result data is generated by a running *Program*. The result data can be intermediate or final. Result data may be associated with specific *Program* state transitions.

#### 4.2.9.2 Intermediate result data

Intermediate result data is transient and is generated by the *Program* in conjunction with nonterminal state transitions. The data items that compose the intermediate results are defined in association with specific *Program* state transitions. Their values are relevant only at the transition level.

Each *Program* state transition can be associated with different result data items. Alternately, a set of transitions can share a result data item. Percentage complete is an example of intermediate result data. The value of percentage complete is produced when the state transition occurs and is available to the *Client*.

*Clients* acquire intermediate result data by subscribing to *Program* state transition *Events*. The *Events* specify the data items for each transition. When the transition occurs, the generated *Event* conveys the result data values captured to the subscribed *Clients*. If no *Client* is monitoring the *Program*, intermediate result data may be discarded.

# 4.2.9.3 Terminal result data

Terminal result data is the final data generated by the *Program* as it ceases execution. Total execution time, number of widgets produced, and fault condition encountered are examples of terminal result data. When the *Program* enters the terminal state, this result data can be conveyed to the *Client* by the transition *Event*. Terminal result data is also available within the *Program* to be read by a *Client* after the program stops. This data persists until the *Program* Instance is rerun or deleted.

#### 4.2.9.4 Monitoring Programs

*Clients* can monitor the activities associated with a *Program's* execution. These activities include the invocation of the management *Methods*, the generation of result data, and the progression of the *Program* through its states. *Audit Events* are provided for *Method Calls* and state transitions. These *Events* allow a record to be maintained of the *Clients* that interacted with any *Program* and the *Program* state transitions that resulted from that interaction.

#### 4.2.10 Program lifetime

#### 4.2.10.1 Overview

*Programs* can have different lifetimes. Some *Programs* may always be present on a *Server* while others are created and removed. Creation and removal can be controlled by a *Client* or may be restricted to local means.

A *Program* can be *Client* creatable. If a *Program* is *Client* creatable, then the *Client* can add the *Program* to the *Server*. The *Object Create Method* defined in OPC 10000-3, is used to create the *Program* instance. The initial state of the *Program* can be Halted or Ready. Some *Programs*, for example, may require that a resource becomes available after its creation and before it is ready to run. In this case, it would be initialized in the Halted state and transition to Ready when the resource is delivered.

A *Program* can be *Client* removable. If the *Program* is *Client* removable, then the *Client* can delete the *Program* instance from the *Server*. The *DeleteNodes Service* defined in OPC 10000-4 is used to remove the *Program* Instance. The *Program* shall be in a Halted state to be removed. A *Program* may also be auto removable. An auto removable *Program* deletes itself when execution has terminated.

#### 4.2.10.2 **Program instances**

*Programs* can be multiple instanced or single instanced. A *Server* can support multiple instances of a *Program* if these *Program* Instances can be run in parallel. For example, the *Program* may define a *Start Method* that has an input argument to specify which resource is acted upon by its *Functions*. Each instance of the *Program* is then started designating use of different resources. The *Client* can discover all instances of a *Program* that are running on a *Server*. Each instance of a *Program* is uniquely identified on the *Server* and is managed independently by the *Client*.

## 4.2.10.3 Program recycling

*Programs* can be run once or run multiple times (recycled). A *Program* that is run once will remain in the Halted state indefinitely once it has run. The normal course of action would be to delete it following the inspection of its terminal results.

Recyclable *Programs* may have a limited or unlimited cycle count. These *Programs* may require a reset step to transition from the Halted state to the Ready state. This allows for replenishing resources or reinitializing parameters prior to restarting the *Program*. The *Program Control Method* "*Reset*" triggers this state transition and any associated actions or effects.

#### 5 Model

#### 5.1 General

The *Program* model extends the *FiniteStateMachineType* and basic *ObjectType* models presented in OPC 10000-5. Each *Program* has a *Type Definition* that is the subtype of the *FiniteStateMachineType*. The *ProgramStateMachineType* describes the *Finite State Machine* model supported by any *Program Invocation* of that type. The *ProgramStateMachineType* also defines the property set that characterizes specific aspects of that *Program's* behaviour such as lifetime and recycling as well as specifying the result data that is produced by the *Program*.

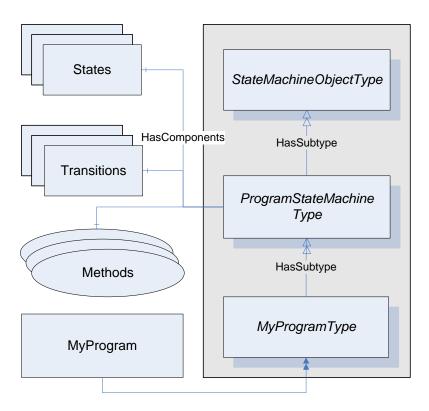


Figure 4 – Program Type

The base *ProgramStateMachineType* defines the standard *Finite State Machine* specified for all *Programs*. This includes the states, transitions, and transition causes (*Methods*) and effects (*Events*). Subtypes of the base *ProgramStateMachineType* can be defined to extend or more specifically characterize the behaviour of an individual *Program* as illustrated with "MyProgramType" in Figure 4.

#### 5.2 ProgramStateMachineType

## 5.2.1 Overview

The additional properties and components that compose the *ProgramStateMachineType* are listed in

Table 5. No *ProgramStateMachineType* specific semantics are assigned to the other base *ObjectType* or *FiniteStateMachineType Attributes* or *Properties*.

Attribute	Value							
	Includes all attributes specified for the FiniteStateMachineType							
BrowseName	ProgramStateMachineType							
IsAbstract	False	False						
References	NodeClass	BrowseName	Data Type	TypeDefinition	Modelling Rule			
HasProperty	Variable	Creatable	Boolean	PropertyType				
HasProperty	Variable	Deletabe	Boolean	PropertyType	Mandatory			
HasProperty	Variable	AutoDelete	Boolean	PropertyType	Mandatory			
HasProperty	Variable	RecycleCount	Int32	PropertyType	Mandatory			
HasProperty	Variable	InstanceCount	UInt32	PropertyType				
HasProperty	Variable	MaxInstanceCount	UInt32	PropertyType				
HasProperty	Variable	MaxRecycleCount	UInt32	PropertyType				
HasComponent	Variable	ProgramDiagnostic	ProgramDiagno stic2DataType	ProgramDiagnos tic2Type	Optional			
HasComponent	Object	Halted		StateType				
HasComponent	Object	Ready		StateType				
HasComponent	Object	Running		StateType				
HasComponent	Object	Suspended		StateType				
Haccomponent	Object	HaltedToReady		TransitionTune				
HasComponent HasComponent	Object			TransitionType TransitionType				
HasComponent	Object	ReadyToRunning RunningToHalted		TransitionType				
		Ŭ						
HasComponent	Object	RunningToReady		TransitionType				
HasComponent	Object	RunningToSuspended		TransitionType				
HasComponent	Object	SuspendedToRunning		TransitionType				
HasComponent	Object	SuspendedToHalted		TransitionType				
HasComponent	Object	SuspendedToReady		TransitionType				
HasComponent	Object	ReadyToHalted		TransitionType				
HasComponent	Method	Start			OptionalPlaceho der			
HasComponent	Method	Suspend			OptionalPlaceho der			
HasComponent	Method	Reset			OptionalPlaceho der			
HasComponent	Method	Halt			OptionalPlaceho der			
HasComponent	Method	Resume			OptionalPlaceho der			
HasComponent	Object	FinalResultData		BaseObjectType	Optional			

### Table 5 – ProgramStateMachineType

## 5.2.2 **ProgramStateMachineType Properties**

The *Creatable Property* is a boolean that specifies if *Program Invocations* of this *ProgramStateMachineType* can be created by a *Client*. If False, these *Program Invocations* are persistent or may only be created by the *Server*.

The Deletable Property is a boolean that specifies if a Program Invocation of this ProgramStateMachineType can be deleted by a Client. If False, these Program Invocations can only be deleted by the Server.

The AutoDelete Property is a boolean that specifies if Program Invocations of this ProgramStateMachineType are removed by the Server when execution terminates. If False, these Program Invocations persist on the Server until they are deleted by the Client. When the Program Invocation is deleted, any result data associated with the instance is also removed.

The *RecycleCount Property* is an unsigned integer that specifies the number of times a *Program Invocation* of this type has been recycled or restarted from its starting point (not resumed). Note that the Reset Method may be required to prepare a *Program* to be restarted.

The *MaxRecycleCount Property* is an integer that specifies the maximum number of times a *Program Invocation* of this type can be recycled or restarted from its starting point (not resumed). If the value is less than 0, then there is no limit to the number of restarts. If the value is zero, then the Program may not be recycled or restarted.

The InstanceCount Property is an unsigned integer that specifies the number of Program Invocations of this type that currently exist.

The *MaxInstanceCount Property* is an integer that specifies the maximum number of *Program Invocations* of this type that can exist simultaneously on this *Server*. If the value is less than 0, then there is no limit.

#### 5.2.3 ProgramStateMachineType components

#### 5.2.3.1 Overview

The *ProgramStateMachineType* components consist of a set of *References* to the *Object* instances of *StateTypes*, *TransitionTypes*, *EventTypes* and the *Methods* that collectively define the *Program FiniteStateMachine*.

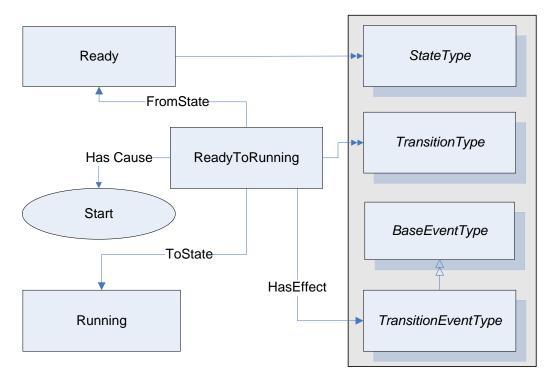


Figure 5 – Program FSM References

Figure 5 illustrates the component *References* that define the associations between two of the *ProgramStateMachineType's* states, Ready and Running. The complementary ReferenceTypes have been omitted to simplify the illustration.

#### 5.2.3.2 ProgramStateMachineType states

Table 6 specifies the *ProgramStateMachineType's* state *Objects*. These *Objects* are instances of the *StateType* defined in OPC 10000-5, Annex B. Each state is assigned a unique *StateNumber* value. Subtypes of the *ProgramStateMachineType* can add references from any state to a subordinate or nested *StateMachine Object* to extend the *FiniteStateMachine*.

BrowseName	References	Target BrowseName	Value	Target TypeDefinition	NOTES
States	·		·	·	•
Halted	HasProperty	StateNumber	11	PropertyType	
	ToTransition	HaltedToReady		TransitionType	
	FromTransition	RunningToHalted		TransitionType	
	FromTransition	SuspendedToHalted		TransitionType	
	FromTransition	ReadyToHalted		TransitionType	
Ready	HasProperty	StateNumber	12	PropertyType	
	FromTransition	HaltedToReady		TransitionType	
	ToTransition	ReadyToRunning		TransitionType	
	FromTransition	RunningToReady		TransitionType	
	ToTransition	ReadyToHalted		TransitionType	
Running	HasProperty	StateNumber	13	PropertyType	
	ToTransition	RunningToHalted		TransitionType	
	ToTransition	RunningToReady		TransitionType	
	ToTransition	RunningToSuspended		TransitionType	
	FromTransition	ReadyToRunning		TransitionType	
	FromTransition	SuspendedToRunning		TransitionType	
Suspended	HasProperty	StateNumber	14	PropertyType	
	ToTransition	SuspendedToRunning		TransitionType	
	ToTransition	SuspendedToHalted		TransitionType	
	ToTransition	SuspendedToReady		TransitionType	
	FromTransition	RunningToSuspended		TransitionType	

Table 6 – Program states

The Halted state is the idle state for a *Program*. It can be an initial state or a terminal state. As an initial state, the *Program Invocation* cannot begin execution due to conditions at the *Server*. As a terminal state, Halted can indicate either a failed or completed *Program*. A subordinate state or result can be used to distinguish the nature of the termination. The Halted state references four *Transition Objects*, which identify the allowed state transitions to the Ready state and from the Ready, Running, and Suspended states.

The Ready state indicates that the *Program* is prepared to begin execution. *Programs* that are ready to begin upon their creation may transition immediately to the Ready state. The Ready state references four *Transition Objects*, which identify the allowed state transitions to the Running and Halted states and from the Halted and Ready states.

The Running state indicates that the *Program* is actively performing its *Function*. The Running state references five *Transition Objects*, which identify the allowed state transitions to the Halted, Ready, and Suspended states and from the Ready and Suspended states.

The Suspended state indicates that the *Program* has stopped performing its *Function*, but retains the ability to resume the *Function* at the point at which it was executing when suspended.

The Suspended state references four *Transition Objects*, which identify the allowed state transitions to the Ready, Running, and Halted state and from the Ready state.

#### 5.2.3.3 **ProgramStateMachineType transitions**

*ProgramStateMachineType* Transitions are instances of the *TransitionType* defined in OPC 10000-5 which also includes the definitions of the ToState, FromState, HasCause, and HasEffect references used. Table 7 specifies the transitions defined for the *ProgramStateMachineType*. Each transition is assigned a unique *TransitionNumber*. The Notes column indicates when a cause is referencing *Methods* and when effects are optional.

BrowseName	References	Target BrowseName	Value	Target TypeDefinition	Notes
Transitions					
HaltedToReady	HasProperty	TransitionNumber	1	PropertyType	
	ToState	Ready		StateType	
	FromState	Halted		StateType	
	HasCause	Reset			Method
	HasEffect	ProgramTransitionEventType			
	HasEffect	AuditProgramTransitionEventType			
ReadyToRunning	HasProperty	TransitionNumber	2	PropertyType	
	ToState	Running		StateType	
	FromState	Ready		StateType	
	HasCause	Start			Method
	HasEffect	ProgramTransitionEventType			
	HasEffect	AuditProgramTransitionEventType			
RunningToHalted	HasProperty	TransitionNumber	3	PropertyType	
	ToState	Halted		StateType	
	FromState	Running		StateType	
	HasCause	Halt			Method
	HasEffect	ProgramTransitionEventType			
	HasEffect	AuditProgramTransitionEventType			
RunningToReady	HasProperty	TransitionNumber	4	PropertyType	
	ToState	Ready		StateType	
	FromState	Runnning		StateType	
	HasEffect	ProgramTransitionEventType			
	HasEffect	AuditProgramTransitionEventType			
RunningToSuspend ed	HasProperty	TransitionNumber	5	PropertyType	
	ToState	Running		StateType	
	FromState	Suspended		StateType	
	HasCause	Suspend			Method
	HasEffect	ProgramTransitionEventType			
	HasEffect	AuditProgramTransitionEventType			

#### Table 7 – Program transitions

BrowseName	References	Target BrowseName	Value	Target TypeDefinition	Notes
SuspendedToRunni ng	HasProperty	TransitionNumber	6	PropertyType	
	ToState	Running		StateType	
	FromState	Suspended		StateType	
	HasCause	Resume			Method
	HasEffect	ProgramTransitionEventType			
	HasEffect	AuditProgramTransitionEventType			
SuspendedToHalted	HasProperty	TransitionNumber	7	PropertyType	
	ToState	Halted		StateType	
	FromState	Suspended		StateType	
	HasCause	Halt			Method
	HasEffect	ProgramTransitionEventType			
	HasEffect	AuditProgramTransitionEventType			
SuspendedToReady	HasProperty	TransitionNumber	8	PropertyType	
	ToState	Ready		StateType	
	FromState	Suspended		StateType	
	HasCause	Reset			Method
	HasEffect	ProgramTransitionEventType			
	HasEffect	AuditProgramTransitionEventType			
DeedsTallakad	Lies Dren entry	TransitionNumber	0	Dream anth Turn a	
ReadyToHalted	HasProperty	TransitionNumber	9	PropertyType	
	ToState	Halted		StateType	
	FromState	Ready		StateType	
	HasCause	Halt			Method
	HasEffect	ProgramTransitionEventType			
	HasEffect	AuditProgramTransitionEventType			

The *HaltedToReady* transition specifies the transition from the Halted to Ready states. It may be caused by the *Reset Method*.

The *ReadyToRunning* transition specifies the transition from the Ready to *Running* states. It is caused by the *Start Method*.

The *RunningToHalted* transition specifies the transition from the *Running* to Halted states. It is caused by the *Halt Method*.

The *RunningToReady* transition specifies the transition from the Running to Ready states. The *RunningToSuspended* transition specifies the Transition from the Running to Suspended states. It is caused by the *Suspend Method*.

The *SuspendedToRunning* transition specifies the transition from the Suspended to Running states. It is caused by the *Resume Method*.

The *SuspendedToHalted* transition specifies the transition from the Suspended to Halted states. It is caused by the *Halt Method*.

The *SuspendedToReady* transition specifies the transition from the Suspended to Ready states. It is caused internally.

The *ReadyToHalted* transition specifies the transition from the Ready to Halted states. It is caused by the *Halt Method*.

Two HasEffect references are specified for each Program transition. These effects are Events of ProgramTransitionEventType and AuditProgramTransitionEventType defined in 5.2.5. The ProgramTransitionEventType notifies Clients of the Program transition and conveys result data. The AuditProgramTransitionEventType is used to audit transitions that result from Program Control Methods. The "Audit Server Facet" Profile defined in OPC 10000-7 requires support of the AuditProgramTransitionEventType.

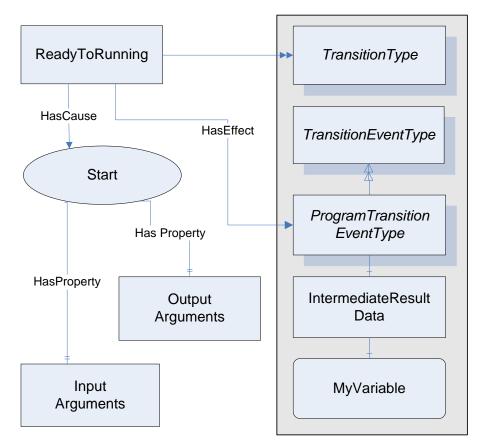


Figure 6 – ProgramStateMachineType causes and effects

#### 5.2.4 **ProgramStateMachineType causes (Methods)**

#### 5.2.4.1 Overview

The ProgramStateMachineType includes references to the Causes of specific Program state transitions. These causes refer to *Method* instances. *Programs* that do not support a *Program* Control Method will omit the Causes reference to that Method from the ProgramStateMachineType references. If a Method's Causes reference is omitted from the ProgramStateMachineType then a Client cannot cause the associated state transition. The Method instances referenced by the ProgramStateMachineType identify the InputArguments and OutputArguments required for the Method calls to Program Invocations of that ProgramStateMachineType. Table 8 specifies the Methods defined as Causes for ProgramStateMachineTypes. Figure 6 illustrates the References associating the components and Properties of Methods and Events with Program transitions.

BrowseName	References	Target BrowseName	Value	Target TypeDefinition	NOTES			
Causes								
Start	HasProperty	InputArguments		PropertyType	Optional			

Table 8 – ProgramStateMachineType causes

BrowseName	References	Target BrowseName	Value	Target TypeDefinition	NOTES
	HasProperty	OutputArguments		PropertyType	Optional
Suspend	HasProperty	InputArguments		PropertyType	Optional
	HasProperty	OutputArguments		PropertyType	Optional
Resume	HasProperty	InputArguments		PropertyType	Optional
	HasProperty	OutputArguments		PropertyType	Optional
Halt	HasProperty	InputArguments		PropertyType	Optional
	HasProperty	OutputArguments		PropertyType	Optional
Reset	HasProperty	InputArguments		PropertyType	Optional
	HasProperty	OutputArguments		PropertyType	Optional

The Start Method causes the ReadyToRunning Program transition.

The Suspend Method causes the RunningToSuspended Program transition.

The Resume Method causes the SuspendedToRunning Program transition.

The Halt Method causes the RunningToHalted, SuspendedToHalted, or ReadyToHalted Program transition depending on the current state of the Program.

The Reset Method causes the HaltedToReady Program transition.

#### 5.2.4.2 Standard attributes

The *Executable Method* attribute indicates if a method can currently be executed. For *Program Control Methods*, this means that the owning *Program* has a current state that supports the transition caused by the *Method*.

#### 5.2.4.3 Standard properties

#### 5.2.4.3.1 Overview

Methods can reference a set of InputArguments. For each ProgramStateMachineType, a set of InputArguments may be defined for the supported Program Control Methods. The data passed in the arguments supplements the information required by the Program to perform its Function. All calls to a Program Control Method for each Program Invocation of that ProgramStateMachineType shall pass the specified arguments.

Methods can reference a set of OutputArguments. For each ProgramStateMachineType, a set of OutputArguments is defined for the supported Program Control Methods. All calls to a Program Control Method for each Program Invocation of that ProgramStateMachineType shall pass the specified arguments.

#### 5.2.5 **ProgramStateMachineType effects (Events)**

#### 5.2.5.1 Overview

The *ProgramStateMachineType* includes component references to the Effects of each of the *Program's* state transitions. These Effects are *Events*. Each *Transition* shall have a *HasEffect Reference* to a *ProgramTransitionEventType* and can have an *AuditProgramTransitionEventType*. When the transition occurs, *Event* notifications of the referenced type are generated for subscribed *Clients*. The *Program Invocation* may serve as the *EventNotifier* for these *Events* or an owning *Object* or the *Server Object* may provide the notifications.

*ProgramTransitionEventTypes* provide the means for delivering result data and confirming state transitions for subscribed *Clients* on each defined *Program State Transition*. The *AuditProgramTransitionEventType* allows the auditing of changes to the *Program*'s state in conjunction with *Client Method Calls*.

## 5.2.5.2 **ProgramTransitionEventType**

The *ProgramTransitionEventType* is a subtype of the *TransitionEventType*. It is used with *Programs* to acquire intermediate or final results or other data associated with a state transition. A *Program* can have a unique *ProgramTransitionEventType* definition for any transition. Each *ProgramTransitionEventType* specifies the *IntermediateResult* data specific to the designated state transition on that *ProgramStateMachineType*. Each transition can yield different intermediate result data. Table 9 specifies the *ProgramTransitionEventType*.

Table 10 identifies the *ProgramTransitionEventTypes* that are specified for *ProgramStateMachineTypes*.

Attribute	Value							
BrowseName	ProgramTran	ProgramTransitionEventType						
IsAbstract	True	True						
References	NodeClass BrowseName		DataType	TypeDefinition	ModellingRule			
Subtype of the base TransitionEventType defined in OPC 10000-5.								
HasComponent	Object	IntermediateResult		BaseObjectType	Optional			

#### Table 9 – ProgramTransitionEventType

*TransitionNumber* identifies the *Program* transition that triggered the *Event*.

FromStateNumber identifies the state before the Program transition.

ToStateNumber identifies the state after the Program transition.

The IntermediateResult is an Object that aggregates a set of Variables whose values are relevant for the Program at the instant of the associated transition. The ObjectType for the IntermediateResult specifies the collection of Variables using a set of HasComponent References.

Table	10 – Progran	mTransitionEvent	S

BrowseName	References	Target BrowseName	Value	Target TypeDefinition	Notes
Effects					
HaltedToReadyEvent					
	HasProperty	TransitionNumber	1	PropertyType	
	HasProperty	FromStateNumber	1	PropertyType	
	HasProperty	ToStateNumber	2	PropertyType	
	HasComponent	IntermediateResults		ObjectType	Optional
ReadyToRunningEvent					
	HasProperty	TransitionNumber	2	PropertyType	
	HasProperty	FromStateNumber	2	PropertyType	
	HasProperty	ToStateNumber	3	PropertyType	
	HasComponent	IntermediateResults		ObjectType	Optional
RunningToHaltedEvent					
	HasProperty	TransitionNumber	3	PropertyType	
	HasProperty	FromStateNumber	3	PropertyType	
	HasProperty	ToStateNumber	1	PropertyType	
	HasComponent	IntermediateResults	-	ObjectType	Optional
RunningToReadyEvent					
Running Forceauy_vent	HasProperty	TransitionNumber	4	PropertyType	
	HasProperty	FromStateNumber	3	PropertyType	
	HasProperty	ToStateNumber	2	PropertyType	
	HasComponent	IntermediateResults	2	ObjectType	Optional
RunningToSuspendedEve nt					
	HasProperty	TransitionNumber	5	PropertyType	
	HasProperty	FromStateNumber	3	PropertyType	
	HasProperty	ToStateNumber	4	PropertyType	
	HasComponent	IntermediateResults		ObjectType	Optional
SuspendedToRunningEve nt					
	HasProperty	TransitionNumber	6	PropertyType	
	HasProperty	FromStateNumber	4	PropertyType	
	HasProperty	ToStateNumber	3	PropertyType	
	HasComponent	IntermediateResults		ObjectType	Optiona
SuspendedToHaltedEvent					
	HasProperty	TransitionNumber	7	PropertyType	
	HasProperty	FromStateNumber	4	PropertyType	
	HasProperty	ToStateNumber	1	PropertyType	
	HasComponent	IntermediateResults		ObjectType	Optional

BrowseName	References	Target BrowseName	Value	Target TypeDefinition	Notes
SuspendedToReadyEvent					
	HasProperty	TransitionNumber	8	PropertyType	
	HasProperty	FromStateNumber	4	PropertyType	
	HasProperty	ToStateNumber	2	PropertyType	
	HasComponent	IntermediateResults		ObjectType	Optional
ReadyToHaltedEvent					
	HasProperty	TransitionNumber	9	PropertyType	
	HasProperty	FromStateNumber	2	PropertyType	
	HasProperty	ToStateNumber	1	PropertyType	
	HasComponent	IntermediateResults		ObjectType	Optional

#### 5.2.6 AuditProgramTransitionEventType

The AuditProgramTransitionEventType is a subtype of the AuditUpdateStateEventType. It is used with Programs to provide a means to audit the Program State transitions associated with any Client invoked Program Control Method. Servers shall generate AuditProgramTransitionEvents if they support the Audit Server Facet Profile defined in OPC 10000-7.

Table 11 specifies the definition of the *AuditProgramTransitionEventType*.

Attribute	Value							
BrowseName	AuditProgram	AuditProgramTransitionEventType						
IsAbstract	True	True						
References	NodeClass	BrowseName	DataType	TypeDefinition	ModellingRule			
Subtype of the AuditUpdateStateEventType defined in OPC 10000-5.								
HasProperty	Variable	TransitionNumber	UInt32	PropertyType	Mandatory			

#### Table 11 – AuditProgramTransitionEventType

This *EventType* inherits all *Properties* of the *AuditUpdateStateEventType* defined in OPC 10000-5, except as noted below.

The *Status Property,* specified in OPC 10000-5,, identifies whether the state transition resulted from a Program Control Method call (set *Status* to TRUE) or not (set *Status* to FALSE).

The SourceName specified in OPC 10000-5, identifies the Method causing the Program transition when it is the result of a *Client* invoked *ProgramControlMethod*. The SourceName is prefixed with "Method/" and the name of the *ProgramControlMethod*, "Method/Start" for example.

The *ClientUserId Property,* specified in OPC 10000-5, identifies the user of the *Client* that issued the *Program Control Method* if it is associated with this *Program* state transition.

The *ActionTimeStamp Property,* specified in OPC 10000-5 "AuditEventType", identifies when the time the *Program* state transition that resulted in the *Event* being generated occurred.

The *TransitionNumber Property* is a *Variable* that identifies the transition that triggered the *Event*.

#### 5.2.7 FinalResultData

The *FinalResultData ObjectType* specifies the *VariableTypes* that are preserved when the *Program* has completed its *Function*. The *ObjectType* includes *a HasComponent* for a *VariableType* of each *Variable* that comprises the final result data.

#### 5.2.8 ProgramDiagnostic2 DataType

This structure contains elements that chronicle the *Program Invocation's* activity and can be used to aid in the diagnosis of *Program* problems.

Note The original ProgramDiagnosticDataType had flaws. To avoid collisions with existing implementations, a new version with name ProgramDiagnostic2DataType has been created.

Its composition is defined in Table 12.

Name	Туре	Description
ProgramDiagnostic2DataType	structure	
createSessionId	Nodeld	The CreateSessionId contains the SessionId of the Sessionon which the call to the Create Method was issued to create the Program Invocation.
createClientName	String	The CreateClientName is the name of the Clientof the Sessionthat created the Program Invocation.
invocationCreationTime	UTCTime	The InvocationCreationTime identifies the time the Program Invocation was created.
lastTransitionTime	UTCTime	The LastTransitionTime identifies the time of the last Program state transition that occurred.
lastMethodCall	String	The LastMethodCall identifies the last Program Method called on the Program Invocation.
lastMethodSessionId	Nodeld	The LastMethodSessionId contains the SessionId of the Sessionon which the last Program Control Method call to the Program Invocation was issued.
lastMethodInputArguments	Argument[]	The LastMethodInputArguments provides the input arguments on the last Program Method call.
lastMethodOutputArguments	Argument[]	The LastMethodOutputArguments provides the output arguments on the last Program Method call.
lastMethodInputValues	BaseDataType []	The LastMethodInputValues preserves the values of the input arguments on the last Program Method call. The size and order of this list matches the size and order of the lastMethodInputArguments field.
lastMethodOutputValues	BaseDataType []	The LastMethodOutputValues preserves the values of the output arguments on the last Program Method call. The size and order of this list matches the size and order of the lastMethodOutputArguments field.
lastMethodCallTime	UTCTime	The LastMethodCallTime identifies the time of the last Method call to the Program Invocation.
lastMethodReturnStatus	StatusCode	The LastMethodReturnStatus preserves the value of the return status for the last Program Control Method requested for this Program Invocation.

Table 12 – ProgramDiagnostic2DataType structure

Its representation in the AddressSpace is defined in Table 13.

#### Table 13 – ProgramDiagnostic2DataType definition

Attributes	Value
BrowseName	ProgramDiagnostic2DataType

#### 5.2.9 ProgramDiagnostic2Type VariableType

This *VariableType* aggregates simple *Variables* using simple *DataTypes* that reflect the elements of the ProgramDiagnosticDataType structure. Its *DataVariables* have the same semantic as defined in in 5.2.8.

Note The original ProgramDiagnosticType VariableType had the same flaws as the structure. To avoid collisions with existing implementations, a new version with name ProgramDiagnostic2Type has been created.

The VariableType is formally defined in Table 14.

Attribute		Value				
BrowseName	ProgramDiag	nostic2Type				
IsAbstract	False					
References	NodeClass	BrowseName	DataType / TypeDefinition	Modelling Rule		
Subtype of the Ba	aseDataVariabl	eType defined in OPC 10000-5.				
HasComponent	Variable	CreateSessionId	Nodeld	Mandatory		
HasComponent	Variable	CreateClientName	String	Mandatory		
HasComponent	Variable	InvocationCreationTime	UTCTime	Mandatory		
HasComponent	Variable	LastTransitionTime	UTCTime	Mandatory		
HasComponent	Variable	LastMethodCall	String	Mandatory		
HasComponent	Variable	LastMethodSessionId	Nodeld	Mandatory		
HasComponent	Variable	LastMethodInputArguments	Argument[]	Mandatory		
HasComponent	Variable	LastMethodOutputArguments	Argument[]	Mandatory		
HasComponent	Variable	LastMethodInputValues	BaseDataType[]	Mandatory		
HasComponent	Variable	LastMethodOutputValues	BaseDataType[]	Mandatory		
HasComponent	Variable	LastMethodCallTime	UTCTime	Mandatory		
HasComponent	Variable	LastMethodReturnStatus	StatusCode	Mandatory		

Table 14 – ProgramDiagnostic2Type VariableType

# 22

#### Annex A (informative)

# **Program example**

#### A.1 Overview

This example illustrates the use of a *Program* to manage a domain download into a control system as depicted in Figure A.1. The download requires the segmented transfer of control operation data from a secondary storage device to the local memory within a control system.

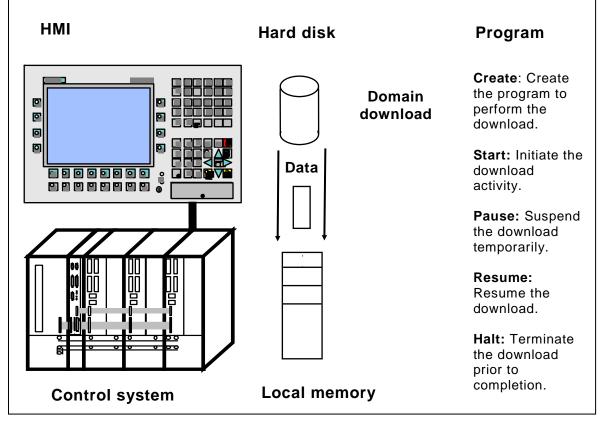


Figure A.1 – Program example

The domain download has a source and a target location which are identified when the download is initiated. Each time a segment of the domain is successfully transferred the *Client* is notified and informed of the amount of data that has been downloaded. The *Client* is also notified when the download is finished. The percentage of the total data received is reported periodically while the download continues. If the download fails, the cause of the failure is reported. At the completion of the download, the performance information is kept at the *Server*.

# A.2 DomainDownload Program

#### A.2.1 General

The *Client* uses the "DomainDownload" *Program* to manage and monitor the download of a domain at the *Server*.

#### A.2.2 DomainDownload states

The basic state model for the DomainDownload *Program* is presented in Figure A.2. The *Program* has three primary states, Ready, Running, and Halted which are aligned with the standard states of a *ProgramStateMachineType*. Additionally, the *DomainDownloadType* extends the *ProgramStateMachineType* by defining subordinate *State Machines* for the *Program's* Running and Halted states. The subordinate states describe the download

operations in greater detail and allow the *Client* to monitor the activity of the download at a finer resolution.

An instance (*Program Invocation*) of a DomainDownload *Program* is created by the *Client* each time a download is to be performed. The instance exists until explicitly removed by the *Client*. The initial state of the *Program* is Ready and the terminal state is Halted. The DomainDownload can be temporarily suspended and then resumed or aborted. Once halted, the program may not be restarted.

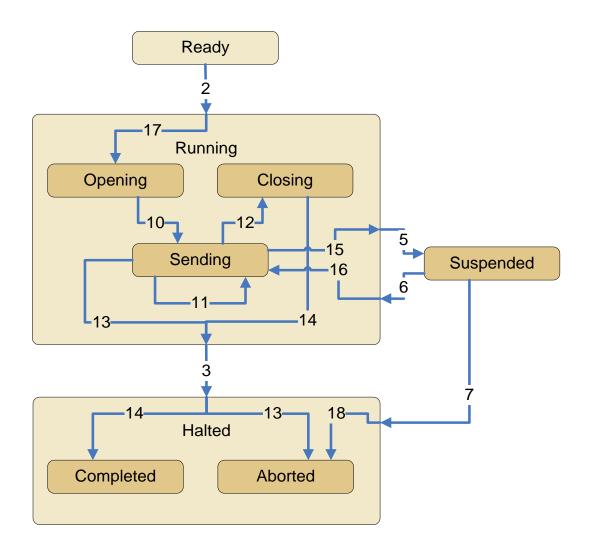


Figure A.2 – DomainDownload state diagram

The sequence of state transitions is illustrated in Figure A.2. Once the download is started, The *Program* progresses to the Opening state. After the source of the data is opened, a sequence of transfers occurs in the Sending state. When the transfer completes the *Objects* are closed in the Closing state. If the transfer is terminated before all of the data is downloaded or an error is encountered then the download is halted and the *Program* transitions to the Aborted state; otherwise the *Program* halts in the Completed state. The states are presented in Table A.1 along with the state transitions.

#### A.2.3 DomainDownload transitions

The valid state transitions specified for the DomainDownload *Program* are specified in Table A.1. Each of the transitions defines a start state and end state for the transition and is identified by a unique number. Five of the transitions are from the base *ProgramStateMachineType* and retain the transition identifier numbers specified for *Programs*. The additional transitions relate the base *Program* states with the subordinate states defined

for the DomainDownload. These states have been assigned unique transition identifier numbers that distinguish them from the base *Program* transition identifiers. In cases where transitions occur between substates and the *Program's* base states, two transitions are specified. One transition identifies the base state change and a second sub-state change. For example, Ready to Running and to Opening occurs at the same time.

The table also specifies the defined states, causes for the transitions, and the effects of each transition. *Program Control Methods* are used by the *Client* to "run" the DomainDownload. The *Methods* cause or trigger the specified transitions. The transition effects are the specified *EventTypes* which notify the *Client* of *Program* activity.

No.	Transition name	Cause	From State	To State	Effect
2	ReadyToRunning	Start Method	Ready	Running	Report Transition 2 Event/Result
3	RunningToHalted	Halt Method/Error or Internal.	Running	Halted	Report Transition 3 Event/Result
5	RunningToSuspended	Suspend Method	Running	Suspended	Report Transition 5 Event/Result
6	SuspendedToRunning	Resume Method	Suspended	Running	Report Transition 6 Event/Result
7	SuspendedToHalted	Halt Method	Suspended	Halted	Report Transition 7 Event/Result
10	OpeningToSending	Internal	Opening	Sending	Report Transition 10 Event/Result
11	SendingToSending	Internal	Sending	Sending	Report Transition 11 Event/Result
12	SendingToClosing	Internal	Sending	Closing	Report Transition 12 Event/Result
13	SendingToAborted	Halt Method/Error	Opening	Aborted	Report Transition 13 Event/Result
14	ClosingToCompleted	Internal	Closing	Completed	Report Transition 14 Event/Result
15	SendingToSuspended	Suspend Method	Sending	Suspended	Report Transition 16 Event/Result
16	SuspendedToSending	Resume Method	Suspended	Sending	Report Transition 17 Event/Result
18	SuspendedToAborted	Halt Method	Suspended	Aborted	Report Transition 18 Event/Result
17	ToOpening	Internal	Ready	Opening	Report Transition 19 Event/Result

#### Table A.1 – DomainDownload states

#### A.2.4 DomainDownload Methods

#### A.2.4.1 General

Four standard *Program Methods* are specified for running the DomainDownload *Program, Start, Suspend, Resume, and Halt.* No additional *Methods* are specified. The base behaviours of these *Methods* are defined by the *ProgramStateMachineType*. The *Start Method* initiates the download activity and passes the source and destination locations for the transfer. The *Suspend Method* is used to pause the activity temporarily. The *Resume Method* reinitiates the download, when paused. The *Halt Method* aborts the download. Each of the *Methods* causes a *Program* state transition and a sub state transition. The specific state transition depends on the current state at the time the *Method* has no associated transition, the *Method* returns an error status indicating invalid state for the *Method*.

## A.2.4.2 Method Arguments

The *Start Method* specifies three input arguments to be passed when it is called: Domain Name, DomainSource, and DomainDestination. The other *Methods* require no input arguments. No output arguments are specified for the DomainDownload *Methods*. The resultant error status for the *Program* is part of the *Call Service*.

## A.2.5 DomainDownload Events

#### A.2.5.1 General

A *ProgramTransitionEventType* is specified for each of the DomainDownload *Program* transitions. The *EventTypes* trigger a specific *Event* notification to the *Client* when the associated state transition occurs in the running *Program* Instance. The *Event* notification identifies the transition. The SendingToSending state transition also includes intermediate result data.

# A.2.5.2 Event information

The SendingToSending *Program* transition *Event* relays intermediate result data to the *Client* along with the notification. Each time the transition occurs, data items describing the amount and percentage of data transferred are sent to the *Client*.

#### A.2.5.3 Final result data

The DomainDownload *Program* retains final result data following a completed or aborted download. The data includes the total transaction time and the size of the domain. In the event of an aborted download, the reason for the termination is retained.

#### A.2.6 DomainDownload model

#### A.2.6.1 Overview

The OPC UA model for the DomainDownload *Program* is presented in the following tables and figures. Collectively they define the components that constitute this *Program*. For clarity, the figures present a progression of portions of the model that complement the contents of the tables and illustrate the *Program*'s composition.

The type definition for the DomainDownload *Program* precisely represents the behaviour of the *Program* in terms of OPC UA components. These components can be browsed by a *Client* to interpret or validate the actions of the *Program*.

#### A.2.6.2 DomainDownloadType

The DomainDownloadType is a subtype derived from the *ProgramStateMachineType*. It specifies the use or non-use of optional *ProgramStateMachineType* components, valid extensions such as subordinate *State Machines*, and constrained attribute values applied to instances of DomainDownload *Programs*.

Table A.2 specifies the optional and extended components defined by the DomainDownload Type. Note the references to two sub *State Machine Types*, *TransferStateMachine* and *FinishStateMachine*. The DomainDownloadType omits references to the *Reset Program Control Method* and its associated state transition (HaltedToReady), which it does not support.

Attribute	Value						
	Includes all non-optional attributes specified for the ProgramStateMachineType						
BrowseName	DomainDowr	DomainDownloadType					
IsAbstract	False	False					
References	NodeClass	BrowseName	Data Type	TypeDefinition	Modelling Rule		
HasComponent	Object	TransferStateMachine		StateMachineType	Mandatory		
HasComponent	Object	FinishStateMachine		StateMachineType	Mandatory		
HasComponent	Variable	ProgramDiagnostic		ProgramDiagnostic2Type	Mandatory		
HasComponent	Object	ReadyToRunning		TransitionType			
HasComponent	Object	RunningToHalted		TransitionType			
HasComponent	Object	RunningToSuspended		TransitionType			
HasComponent	Object	SuspendedToRunning		TransitionType			
HasComponent	Object	SuspendedToHalted		TransitionType			
HasComponent	Method	Start			Mandatory		
HasComponent	Method	Suspend			Mandatory		
HasComponent	Method	Halt			Mandatory		
HasComponent	Method	Resume			Mandatory		
HasComponent	Object	FinalResultData		BaseObjectType	Mandatory		

Table A.2 – DomainDownload Type

Table A.3 specifies the *Transfer State Machine type* that is a sub *State Machine* of the DomainDownload *Program Type*. This definition identifies the *StateTypes* that compose the sub states for the *Program's* Running *StateType*.

Table A.3 – Transfer State Machine Ty
---------------------------------------

Attribute	Value				
	Includes all a	ttributes specified for the	FiniteSta	teMachineType	
BrowseName	TransferState	eMachineType			
IsAbstract	False				
References	NodeClass	BrowseName	Data Type	TypeDefinition	Modelling Rule
HasComponent	Object	Opening		StateType	
HasComponent	Object	Sending		StateType	
HasComponent	Object	Closing		StateType	
HasComponent	Object	ReadyToOpening		TransitionType	
HasComponent	Object	OpeningToSending		TransitionType	
HasComponent	Object	SendingToClosing		TransitionType	
HasComponent	Object	SendingToAborted		TransitionType	
HasComponent	Object	SendingToSuspended		TransitionType	
HasComponent	Object	SuspendedToSending		TransitionType	
HasComponent	Method	Start			Mandatory
HasComponent	Method	Suspend			Mandatory
HasComponent	Method	Halt			Mandatory
HasComponent	Method	Resume			Mandatory

Table A.3 specifies the *StateTypes* associated with the Transfer State Machine Type. All of these states are sub states of the *Running* state of the base *ProgramStateMachineType*.

The Opening state is the preparation state for the domain download.

The Sending state is the activity state for the transfer in which the data is moved from the source to destination.

The Closing state is the cleanup phase of the download.

Table A.4 defines the states of the *TransferStateMachineType*.

BrowseName	References	Target BrowseName	Value	Target TypeDefinition	NOTES
States					
Opening	HasProperty	StateNumber	5	PropertyType	
	ToTransition	OpeningToSending		TransitionType	
	FromTransition	ToOpening		TransitionType	
	ToTransition	OpeningToSending		TransitionType	
Sending	HasProperty	StateNumber	6	PropertyType	
	FromTransition	OpeningToSending		TransitionType	
	ToTransition	SendingToSending		TransitionType	
	ToTransition	SendingToClosing		TransitionType	
	ToTransition	SendingToSuspended		TransitionType	
	FromTransition	ToSending		TransitionType	
Closing	HasProperty	StateNumber	7	PropertyType	
	ToTransition	ClosingToCompleted	1	TransitionType	
	ToTransition	ClosingToAborted		TransitionType	
	FromTransition	SendingToClosing		TransitionType	

Table A.4 – Transfer State Machine – states

Table A.5 specifies the *Finish State Machine Type* that is a sub state machine of the DomainDownload *ProgramStateMachineType*. This definition identifies the *StateTypes* that compose the sub states for the *Program's* Halted *StateType*.

Table A.5 – Finish State	Machine Type
--------------------------	--------------

Attribute		Value				
	Includes all a	Includes all attributes specified for the FiniteStateMachineType				
BrowseName	TransferStat	TransferStateMachineType				
IsAbstract	False					
References	NodeClass	BrowseName	Data Type	TypeDefinition	Modelling Rule	
HasComponent	Object	Completed		StateType		
HasComponent	Object	Aborted		StateType		

Table A.6 specifies the *StateTypes* associated with the *Finish State Machine Type*. Note these are final states and that they have no associated transitions between them.

BrowseName	References	Target BrowseName	Value	Target TypeDefinition	NOTES
States					
Aborted	HasProperty	StateNumber	8	PropertyType	
	FromTransition	OpeningToAborted		TransitionType	
	FromTransition	ClosingToAborted		TransitionType	
Completed	HasProperty	StateNumber	9	PropertyType	
	FromTransition	ClosingToCompleted		TransitionType	

Table A.6 – Finish State Machine – states

The Aborted state is the terminal state that indicates an incomplete or failed domain download operation.

The Completed state is the terminal state that indicates a successful domain download.

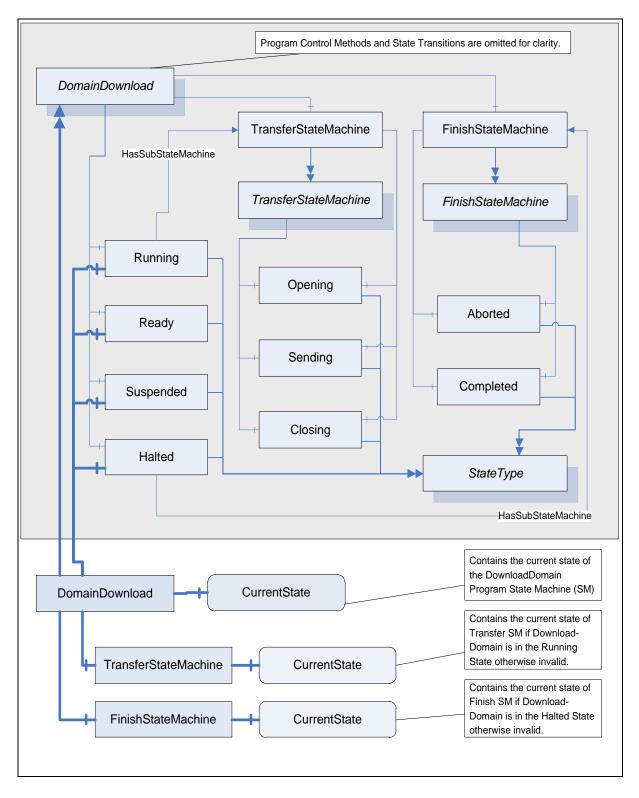
Table A.7 specifies the constraining behaviour of a DomainDownload.

Table A.7 – DomainDownload Type Property Attributes variable values

NodeClass	BrowseName	Data Type	Data Value	Modelling Rule
Variable	Creatable	Boolean	True	
Variable	Deletable	Boolean	True	Mandatory
Variable	AutoDelete	Boolean	False	Mandatory
Variable	RecycleCount	Int32	0	Mandatory
Variable	InstanceCount	UInt32	PropertyType	
Variable	MaxInstanceCount	UInt32	500	
Variable	MaxRecycleCount	UInt32	0	

A DomainDownload *Program Invocation* can be created and also destroyed by a *Client*. The *Program Invocation* will not delete itself when halted, but will persist until explicitly removed by the *Client*. A DomainDownload *Program Invocation* cannot be reset to restart. The *Server* will support up to 500 concurrent DomainDownload *Program Invocation*s.

Figure A.3 presents a partial DomainDownloadType model that illustrates the association between the states and the DomainDownload, Transfer, and Finish State Machines. Note that the current state number for the sub state machines is only valid when the DomainDownload active base state references the sub state machine, Running for the Transfer current state and Halted for the Finish current state.



### Figure A.3 – DomainDownloadType partial state model

Table A.8 specifies the *ProgramTransitionTypes* that are defined in addition to the *ProgramTransitionTypes* specified for *Programs* in Table 7. These types associate the Transfer and Finish sub state machine states with the states of the base *Program*.

BrowseName	References	Target BrowseName	Value	Target TypeDefinition	NOTES
Transitions					•
ToSending	HasProperty	TransitionNumber	10	PropertyType	
	ToState	Sending		StateType	
	FromState	Opening		StateType	
	HasCause	Start			Method
	HasEffect	ProgramTransitionEventType			
	HasEffect	AuditProgramTransitionEventType			
SendingToSending	HasProperty	TransitionNumber	11	PropertyType	
	ToState	Sending		StateType	
	FromState	Sending		StateType	
	HasEffect	ProgramTransitionEventType			
SendingToClosing	HasProperty	TransitionNumber	12	PropertyType	
	ToState	Closing		StateType	
	FromState	Sending		StateType	
	HasEffect	ProgramTransitionEventType			
SendingToAborted	HasProperty	TransitionNumber	13	PropertyType	
	ToState	Aborted		StateType	
	FromState	Sending		StateType	
	HasCause	Halt			Method
	HasEffect	ProgramTransitionEventType			
	HasEffect	AuditProgramTransitionEventType			
ClosingToComplete d	HasProperty	TransitionNumber	14	PropertyType	
	ToState	Completed		StateType	
	FromState	Closing		StateType	
	HasEffect	ProgramTransitionEventType			
SendingToSuspend ed	HasProperty	TransitionNumber	15	PropertyType	
	ToState	Suspended		StateType	
	FromState	Sending		StateType	
	HasCause	Suspend			Method
	HasEffect	ProgramTransitionEventType			
	HasEffect	AuditProgramTransitionEventType			
SuspendedToSendi ng	HasProperty	TransitionNumber	16	PropertyType	
	ToState	Sending		StateType	
	FromState	Suspended	1	StateType	

 Table A.8 – Additional DomainDownload transition types

BrowseName	References	Target BrowseName	Value	Target TypeDefinition	NOTES
Transitions				·	
	HasCause	Resume			Method
	HasEffect	ProgramTransitionEventType			
	HasEffect	AuditProgramTransitionEventType			
SuspendedToAborte d	HasProperty	TransitionNumber	18	PropertyType	
	ToState	Aborted		StateType	
	FromState	Suspended		StateType	
	HasCause	Halt			Method
	HasEffect	ProgramTransitionEventType			
	HasEffect	AuditProgramTransitionEventTy pe			
ReadyToOpening	HasProperty	TransitionNumber	17	PropertyType	
	ToState	Opening		StateType	
	FromState	Ready		StateType	
	HasCause	Start			Method
	HasEffect	ProgramTransitionEventType			
	HasEffect	AuditProgramTransitionEventTy pe			

Figure A.4 through Figure A.10 illustrate portions of the DomainDownloadType model. In each figure, the referenced tates, *Methods*, transitions, and *EventTypes* are identified for one or two state transitions.

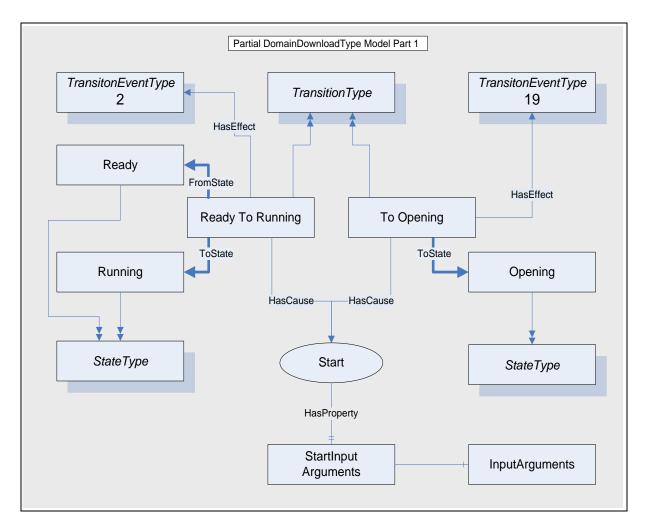


Figure A.4 – Ready To Running model

Figure A.4 illustrates the model for the ReadyToRunning *Program* transition. The transition is caused by the *Start Method*. The *Start Method* requires three input arguments. The *Method Call* service is used by the *Client* to invoke the *Start Method* and pass the arguments. When successful, the *Program Invocation* enters the Running state and the subordinate Transfer Opening state. The *Server* issues two *Event* notifications, ReadyToRunning (2), and ToOpening (19).

Table A.9 – Start Meth	od additions
------------------------	--------------

Attribute	Value				
BrowseName	Start	itart			
IsAbstract	False	False			
References	NodeClass	NodeClass BrowseName DataType TypeDefinition Modelli			ModellingRule
HasProperty	Variable	InputArgument	Argument[]	PropertyType	

Table A.9 specifies that the *Start Method* for the *DomainDownloadType* requires input arguments. Table A.10 identifies the *Start Arguments* required.

Name	Туре	Value
Argument 1	structure	
name	String	SourcePath
dataType	Nodeld	StringNodeld
valueRank	Int32	-1 (-1 = scalar)
arrayDimensions	UInt32[]	null
description	LocalizedText	The source specifier for the domain
Argument 2	structure	
Name	String	DestinationPath
dataType	Nodeld	StringNodeld
valueRank	Int32	-1 (-1 = scalar)
arrayDimensions	UInt32[]	null
description	LocalizedText	The destination specifier for the domain
Argument 3	structure	
name	String	DomainName
dataType	Nodeld	StringNodeld
arrayDimensions	UInt32[]	null
valueRank	Int32	-1 (-1 = scalar)
description	LocalizedText	The name of the domain

Figure A.5 illustrates the model for the Opening To Sending and the Sending to Closing *Program* transitions. As specified in the transition table, these state transitions require no *Methods* to occur, but rather are driven by the internal actions of the *Server*. *Events* are generated for each state transition (10 to 12), when they occur.

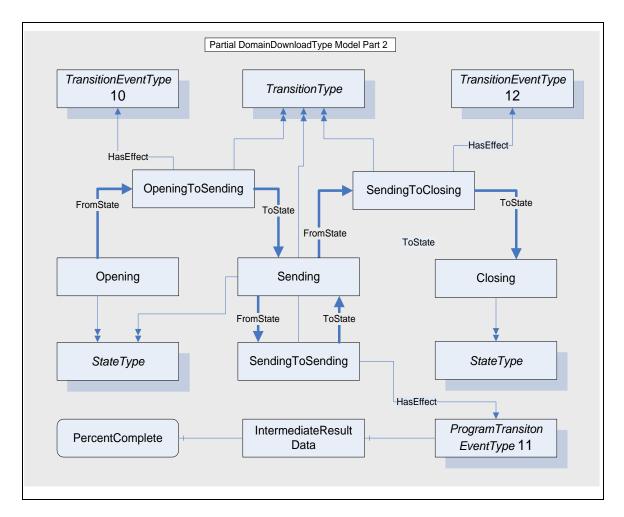


Figure A.5 – Opening To Sending To Closing model

Notice that a state transition can initiate and terminate at the same state (Sending). In this case the transition serves a purpose. The *ProgramTransitionEventType* effect referenced by the SendingToSending state transition has an *IntermediateResultData Object Reference*. The *IntermediateResultData Object* serves to identify two *Variables* whose values are obtained each time the state transition occurs. The values are sent to the *Client* with the *Event* notification. Table A.11 defines the *IntermediateResults ObjectType* and Table A.13 defines the *Variables* of the *ObjectType*.

Attribute	Value				
	Includes all attri	ibutes specified for the Obj	ectType		
BrowseName	IntermediateRe	IntermediateResults			
IsAbstract	False				
References	NodeClass	BrowseName	Data Type	TypeDefinition	Modelling Rule
HasComponent	Variable	AmountTransferred	Long	VariableType	Mandatory
HasComponent	Variable	PercentageTransferred	Long	VariableType	Mandatory

Intermediate Result Variables	Туре	Value
Variable 1	Structure	
Name	String	AmountTransferred
dataType	Nodeld	StringNodeld
description	LocalizedText	Bytes of domain data transferred.
Variable 2 Structure		
Name String		PercentageTransferred
dataType	Nodeld	StringNodeld
description	LocalizedText	Percentage of domain data transferred.

The model for the Running To Suspended state transition is illustrated in Figure A.6. The cause for this transition is the *Suspend Method*. The *Client* can pause the download of domain data to the control. The transition from Running to Suspended invokes the *Event* generation for *TransitionEventTypes* 5 and 16. Note that there is no longer a valid current state for the Transfer State Machine.

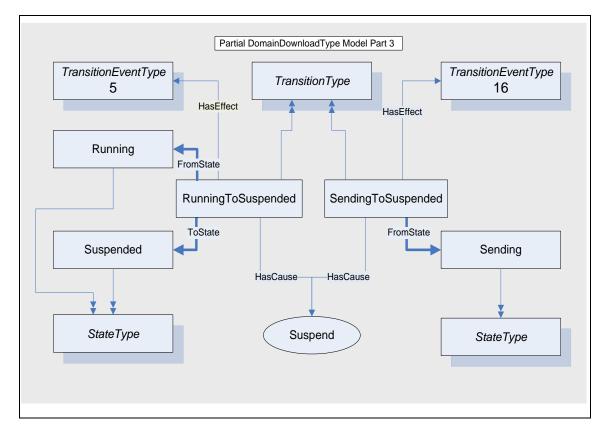
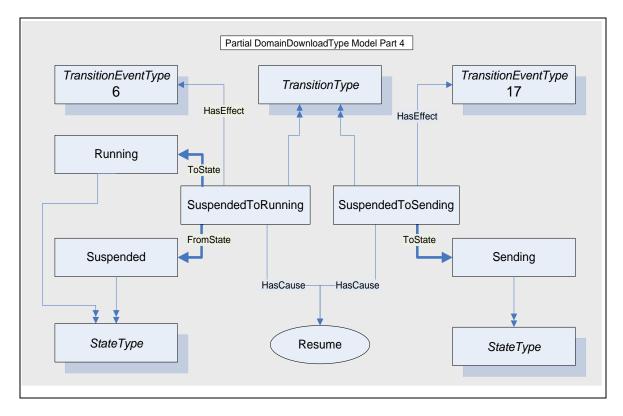


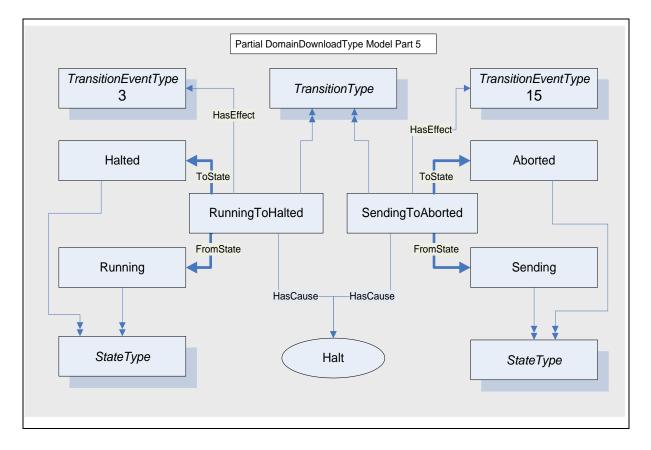
Figure A.6 – Running To Suspended model

The model for the SuspendedToRunning state transition is illustrated in Figure A.7. The cause for this transition is the *Resume Method*. The *Client* can resume the download of domain data to the control. The transition from Suspended to Running generates the *Event* for *TransitionEventTypes* 6 and 17. Now that the Running state is active, the Sending state of the Transfer State Machine is again specified for the *CurrentStateNumber*.



### Figure A.7 – Suspended To Running model

The model for the Running To Halted state transition for an abnormal termination of the domain download is illustrated in Figure A.8. The cause for this transition is the *Halt Method*. The *Client* can terminate the download of domain data to the control. The transition from Running To Halted generates the *Event* for *TransitionEventTypes* 3 and 15. The *TransitionEventType* 15 indicates the transition from the Sending state as the Running State ends and then to the Aborted state as the Halted state is entered.



# Figure A.8 – Running To Halted – Aborted model

Figure A.9 illustrates the model for the Suspended To Halted state transition for an abnormal termination of the domain download. The cause for this transition is the *Halt Method*. The *Client* can terminate the download of domain data to the control while it is suspended. The transition from SuspendedToHalted invokes the *Event* notifiers for *TransitionEventTypes* 7 and 18.

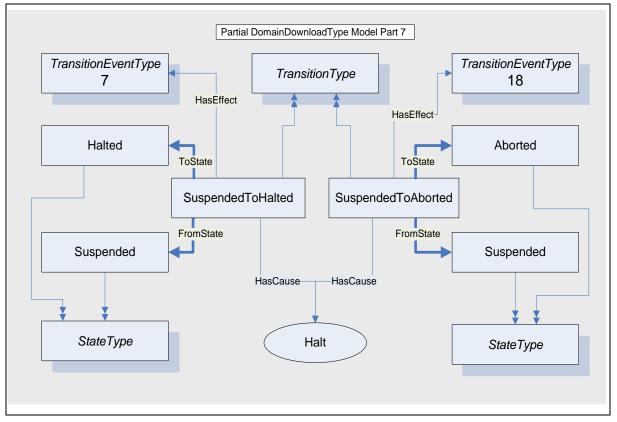


Figure A.9 – Suspended To Aborted model

The model for the Running To Completed state transition for a normal termination of the domain download is illustrated in Figure A.10. The cause for this transition is internal. The transition from Closing To Halted generates the Event for *TransitionEventTypes* 3 and 14. The *TransitionEventType* 14 indicates the transition from the Closing state as the Running state ends and then to the Completed state as the Halted state is entered.

The DomainDownloadType includes a component reference to a *FInalResultData Object*. This *Object* references *Variables* that persists information about the domain download once it has completed. This data can be read by *Clients* who are not subscribed to *Event* notifications. The result data is described in Table A.13.

Attribute	Value				
	Includes all attributes specified for the ObjectType				
BrowseName	FinalResultData				
IsAbstract	False				
References	NodeClass	BrowseName	Data Type	TypeDefinition	Modelling Rule
HasComponent	Variable	DownloadPerformance	Double	VariableType	Mandatory
HasComponent	Variable	FailureDetails	String	VariableType	Mandatory

Table A.13 – FinalResultData

The Domain Download net transfer data rate and detailed reason for aborted downloads is retained as final result data for each *Program Invocation*.

DownloadPerformance provides the data rate in seconds for domain data transferred.

FailureDetails provides a descriptive reason for an abort.

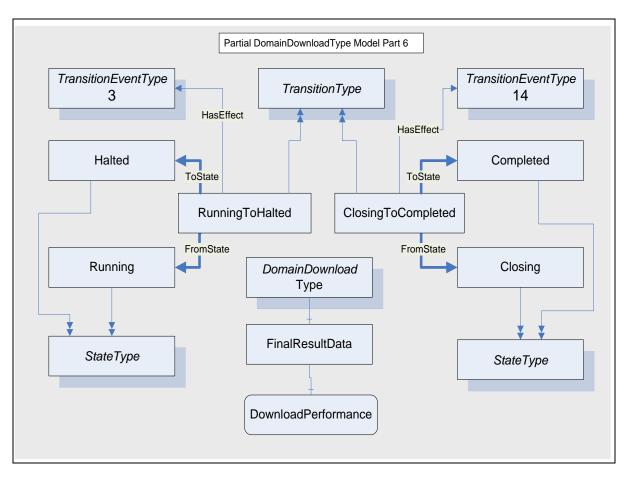
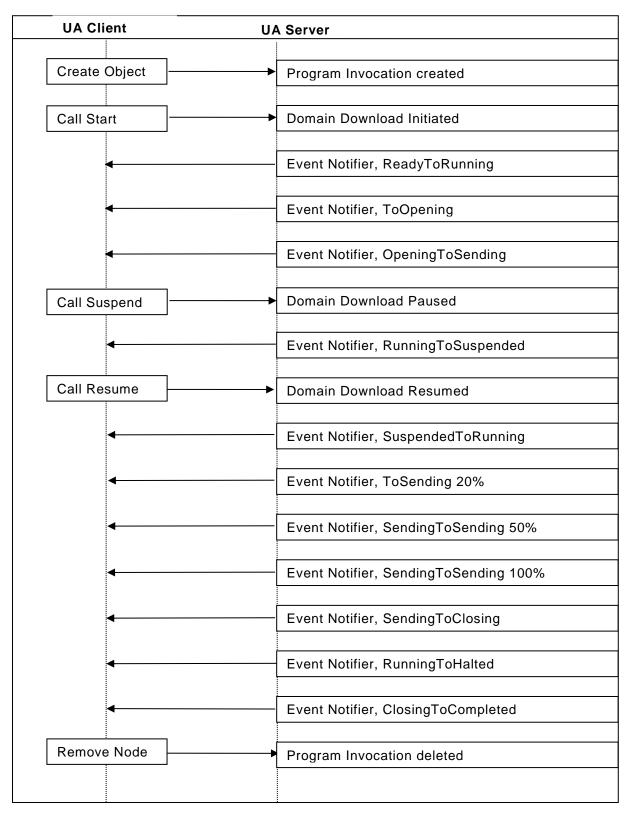


Figure A.10 – Running To Completed model

## A.2.6.3 Sequence of operations

Figure A.11 illustrates a normal sequence of service exchanges between a *Client* and *Server* that would occur during the life cycle of a DomainDownloadType *Program Invocation*.



### Figure A.11 – Sequence of operations